The Revised Sequential Parameter Optimization Toolbox

Thomas Bartz-Beielstein, Martin Zaefferer, Jörg Stork and Sebastian Krey

TH Köln University of Applied Sciences

5th July 2017

Technology Arts Sciences TH Köln



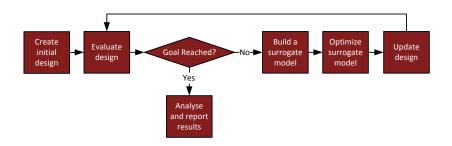
Sequential Parameter Optimization: Overview

- Developed: Bartz-Beielstein et al. (2005)
- Core purpose:
 - Derive understanding of problem, parameters
 - Reduce load of costly target functions
 - Statistically sound comparisons
- Combines approaches from different fields
 - Design of Experiment
 - Statistics
 - Optimization algorithms
- Areas of application
 - Algorithm tuning
 - Engineering design
 - And many more (Bartz-Beielstein, 2010)
- R-package maintained by SPOTSeven research group

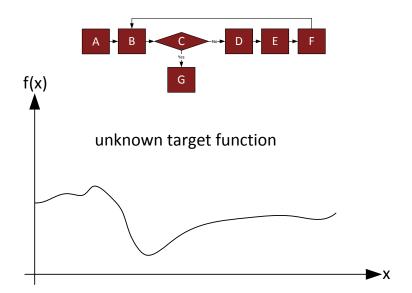


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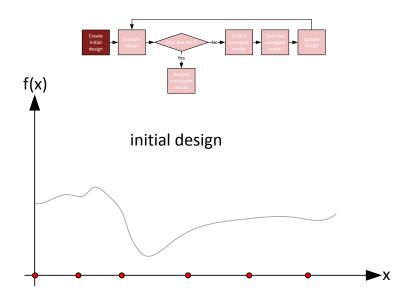
Sequential Parameter Optimization: Concept



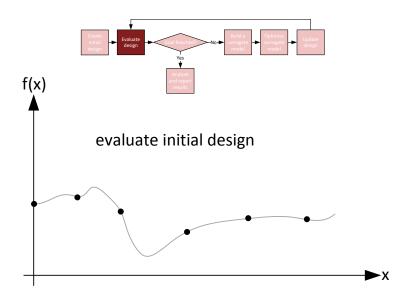






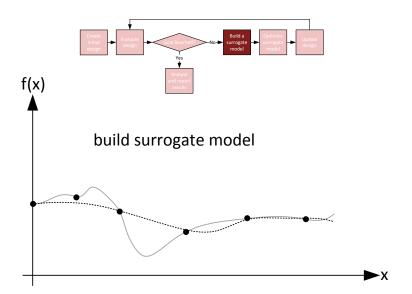




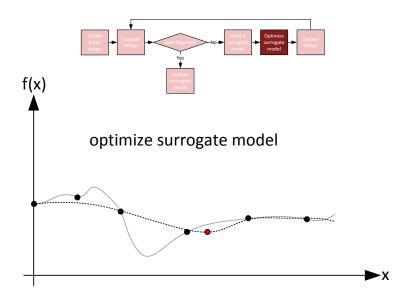




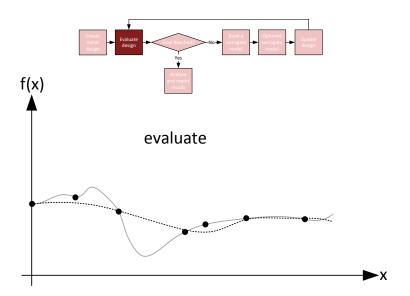
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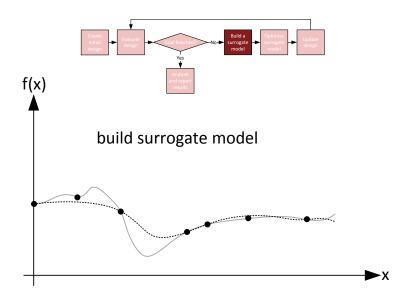






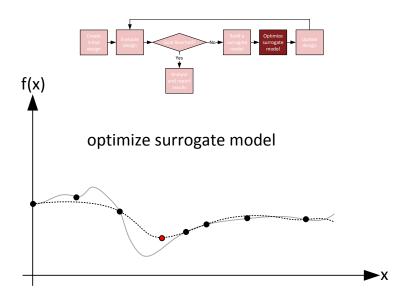




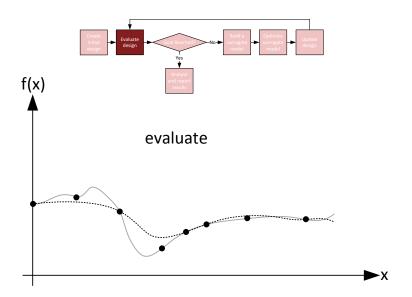




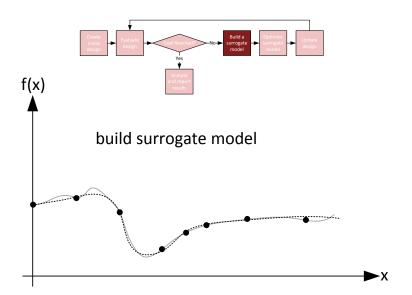
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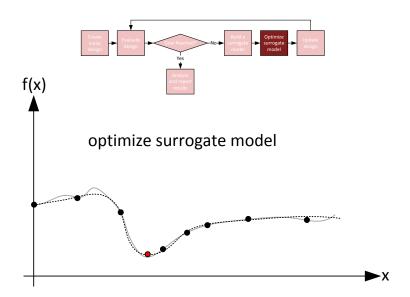




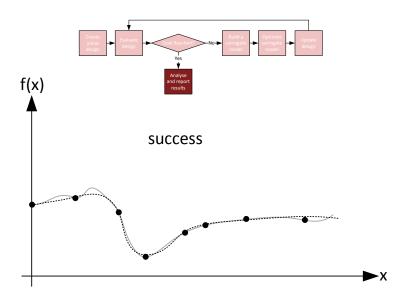














Aims of the revised SPOT package

- High prediction quality
- Stable numerics
- Fast
- Modular structure for good extensibility
- Standardized objects and user interfaces
- Easy comprehensible code
- Good usability



What is new?

- No text files for configuration and data exchange anymore
- Everything implemented in R
- Object-oriented data structures as input and output for the individual functions
- Consistent with core R functionality
- Standardized and modular structure of the functions form a harmonized and easy understandable user interface
- Kriging with categorical inputs
- Stacking of different models for better prediction performance Bartz-Beielstein and Zaefferer (2017)



Create initial design

```
    Arguments

            x: optional matrix of fixed user defined design points
            lower/upper: vectors with boundaries for the design variables
            control: list with the following controls:
            size: number of design points
            retries: number of retries during design creation
            types: vector with the data type for each design parameter
```

designLHD(x = NULL, lower, upper, control = list())

• Returns matrix with design points (rows) for each variable (columns)

replicates: integer for replications of each design point



Model building

Different models can be chosen

- Linear models
- Kriging / Gaussian process regression
- Random Forest
- ...

```
buildKriging(x, y, control = list())
```

Arguments

x: design matrix (sample locations)

y: vector of observations at x

control: list with the options for the model building procedure

 Returns an object of class kriging, basically a list, with the options and found parameters for the model which has to be passed to the predictor function



Optimization

```
    optimLBFGSB(x = NULL, fun, lower, upper, control = list(), ...)
    Wrapper function for optim with method = "L-BFGS-B"
    Arguments

            x: optional matrix of data-points, only first row used as start-point
            fun: objective function, which receives a matrix x and returns observations y
            lower/upper: boundary of the search space control: list of control parameters, passed to optim funEvals: number of function evaluations allowed
```

• Returns list with best solution (xbest, ybest), number of function evaluations (count) and messages from the optimizer



...: passed to fun

Why SPOT instead of package ...

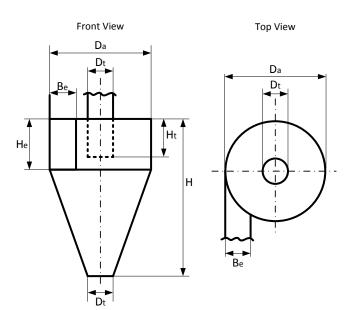
A lot of packages provide methods for model based optimization, Kriging, etc. For example mlrMBO, diceKriging, diceOptim, mleGP, ...

- easy usage
- own Kriging implementation for stable numerics (based on Matlab code from Forrester et al. (2008))
- fast
- good and easy extensibility
- well proven methods for good results in real world problems



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Cyclone optimization





Cyclone optimization

```
funCyclone(c(1260,2500)) #[1] 1626.194527 -0.886269
## create vectorized target funcion for the first objective only
tfunvecF1 <-function(x){apply(x,1,funCyclone)[2,]}
fixed <- matrix(c(1260,2500,1000,2000),2,2,byrow=TRUE)
lower \leftarrow c(1000.2000)
upper \leftarrow c(2000,3000)
## optimize with spot
res <- spot(x = designLHD(x = fixed, lower = lower, upper = upper, co
            fun = tfunvecF1,
            lower = lower,
            upper = upper,
            control = list(modelControl = list(target="ei"),
            model = buildKriging,
            optimizer = optimLBFGSB,
            plots=TRUE))
## best found solution ...
res$xbest #[1,] 2000 2861.775
## ... and its objective function value
res$ybest #[1,] -0.95085
```



Cyclone optimization

A more complex cyclone optimization, building a stacking ensemble of models from lab experiments, CFD simulations and analytical models can be found in Bartz-Beielstein et al. (2016).

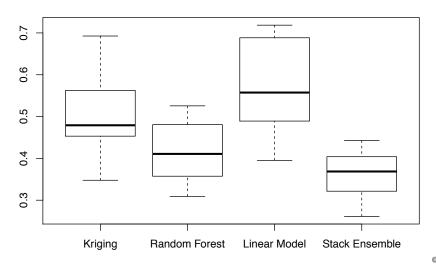
The necessary datasets and the source code for this optimization is available here: http://www.gm.fh-koeln.de/~bartz/Bart16e.d/



Stacking example

```
require(SPOT); require(CEGO)
train <- dataGasSensor[dataGasSensor[,11]==1,1:10]
test <- dataGasSensor[dataGasSensor[,11] == 2,1:10]
  #define an optimizer:
optimizer <- function(x,fun,lower,upper,control,...){</pre>
  CEGO::optimInterface(x, fun, lower, upper,
    control=list(method="NLOPT GN DIRECT L", funEvals=10,
                 reltol=1e-6, restarts=2), ...)
}
fitStack <- buildEnsembleStack(
  data.matrix(train[,c("Y","X7","Sensor","Batch")]),
  data.matrix(train$X1).
  control=list(modelLOControl=list(list(), list(),
                 list(algTheta=optimizer, reinterpolate=FALSE)
predtest <- predict(fitStack,</pre>
  data.matrix(test[,c("Y","X7","Sensor","Batch")]))$y
mse <- mean(abs(predtest - data.matrix(test$X1))^2) # [1] 0.2627
```

Stacking example





Summary and Outlook

- SPOT 2 provides a good base for real world optimization problems
- Interfaces and object structures are stable and allow easy extensions
- Reporting functions are still missing (current work in progress)



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Thank you for your attention!



References

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